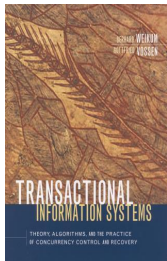


# Transactional Information Systems:

## Theory, Algorithms, and the Practice of Concurrency Control and Recovery

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*“Teamwork is essential. It allows you to blame someone else.”(Anonymous)*

## Part II: Concurrency Control

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# Chapter 9: Concurrency Control on Search Structures

- 9.2 Implementation by B<sup>+</sup>-trees
- 9.3 Key-Range Locking at the Access Layer
- 9.4 Techniques for the Page Layer
- 9.5 Further Optimizations
- 9.6 Lessons Learned

*“ As long as one keeps searching, the answers come. ”*  
*(Joan Baez)*

# Example

$t_1$ :

Update Persons  
Set City = „Phoenix,,  
Where Age  $\geq$  50  
And City = „Dallas,,  
→ modifies record x

$t_2$ :

Select \* From Persons  
Where City = „Phoenix,,  
→ fetches records p, q

Select \* From Persons  
Where City = „Dallas,,  
→ fetches records d, e

## *Observations:*

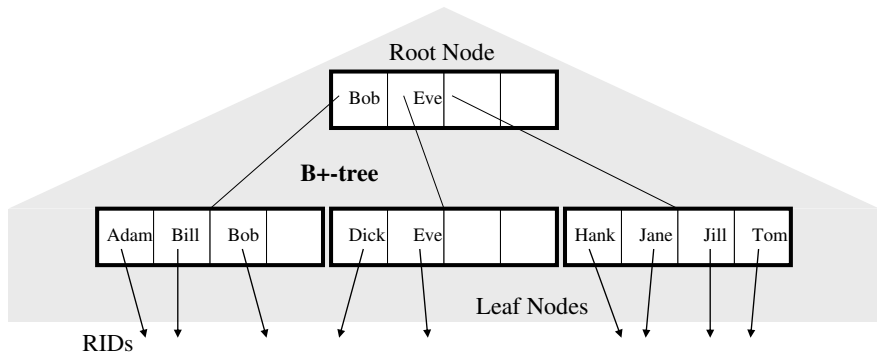
- *page locking would prevent this phantom-problem execution*
- *locking the accessed records alone is insufficient*
- *need appropriate locks on (key, RID) pairs in City index*

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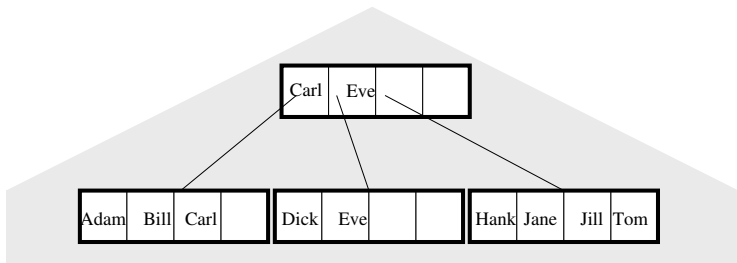
# Implementation of Index by B+-tree



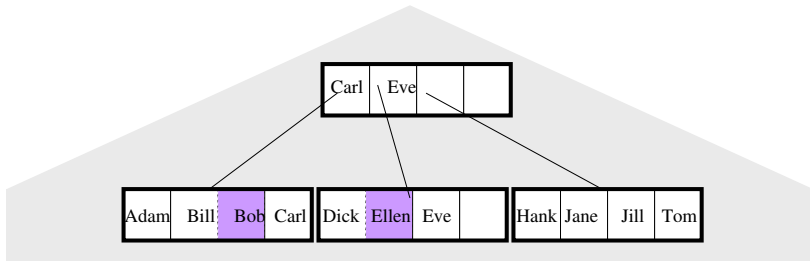
Search tree interface:

- lookup <index> where <indexed field> = <search key>
- lookup <index> where <indexed field>  
between <lower bound> and <higher bound>

# Simple Insertion into B+-tree Index

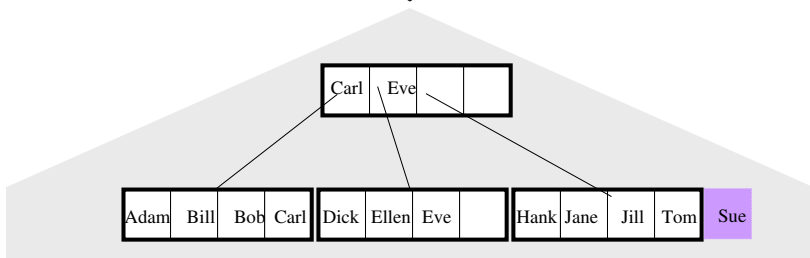


+ Ellen, + Bob



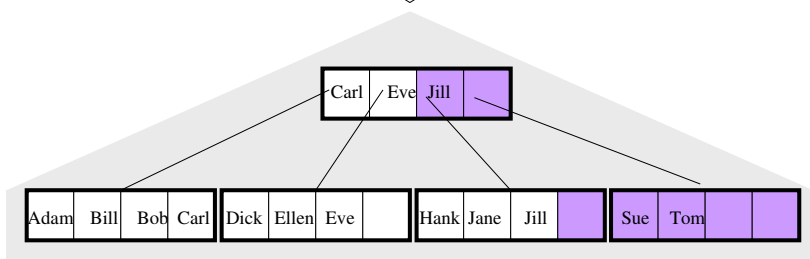
# Insertion into B+-tree with Leaf Node Split

↓ + Sue



**Leaf Node Split**

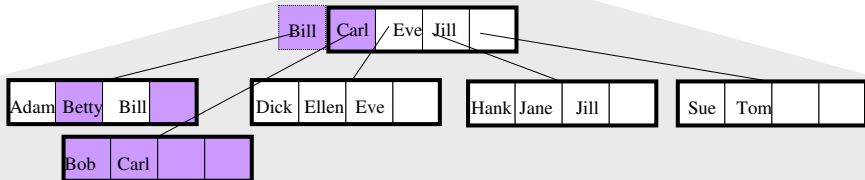
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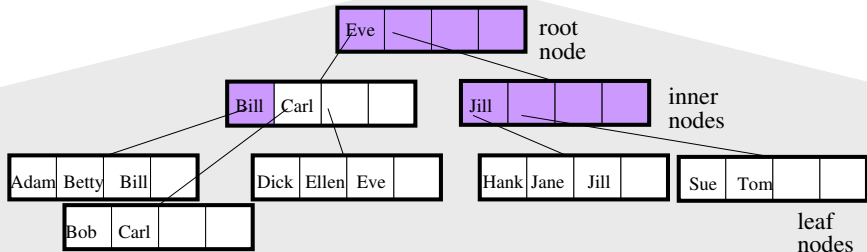
# Insertion into B+-tree with Root Node Split

↓ + Betty



Root Node Split

↓



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# Simple Key-Range Locking

ADT interface for search structure:

*insert (key, RID)*

*delete (key, RID)*

*search (key)*

*range\_search (lowkey, highkey)*

## Protocol:

- insert, delete, and search lock single key  
(insert and delete in compatible modes)
  - range\_search locks interval [lowkey, highkey]
  - table scan effectively locks interval [ -  $\infty$ , +  $\infty$  ]
- + page locks acquired during subtransactions

→ lock manager needs “key in interval” test

→ range\_search “preclaims” lock on entire interval

# Incremental Key-Range Locking

refined ADT interface with

`range_search(lowkey, highkey)` replaced by:

*search (lowkey)  $\uparrow$ key  $\uparrow$ page*

*next (currentkey, currentpage, highkey)  $\uparrow$ key  $\uparrow$ page*

*next ...*

## Approach:

operations lock intervals [found-key, next-existing-key)

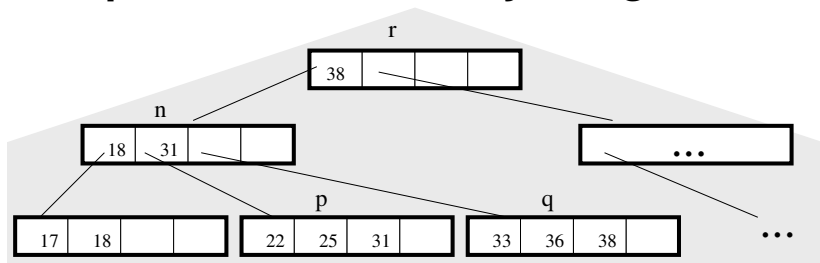
identified by “found-key” (i.e., only keys that do exist in the index)

+ page locks during subtransactions

## Incremental Key-Range (Previous-Key) Locking Protocol:

- `search(x)` requests read lock on `x` if `x` is present, or largest key  $< x$  if `x` is not found
- `next(currentkey, ...)` requests read lock on `currentkey`
- `insert (y, RID)` requests write locks on `y` and largest key  $< y$
- `delete (y, RID)` requests write locks on `y` and largest key  $< y$

# Example: Incremental Key-Range Locking



## **range\_search (23, 34):**

search (23)  $\uparrow$  25  $\uparrow$  p  
lock page r, page n, page p  
lock key 22  
unlock pages r, n, p  
next (25, p, 34)  $\uparrow$  31  $\uparrow$  p  
lock key 25  
next (31, p, 34)  $\uparrow$  33  $\uparrow$  q  
lock key 31  
next (33, q, 34)  $\uparrow$  nil  $\uparrow$  nil  
lock key 33

## **insert (27, ...):**

lock page r, page n, page p  
lock key 25  
lock key 27  
unlock pages r, n, p

# Correctness of Incremental Key-Range Locking

**Theorem 9.1:**

Previous-key locking generates only conflict-serializable schedules as far as index operations are concerned.

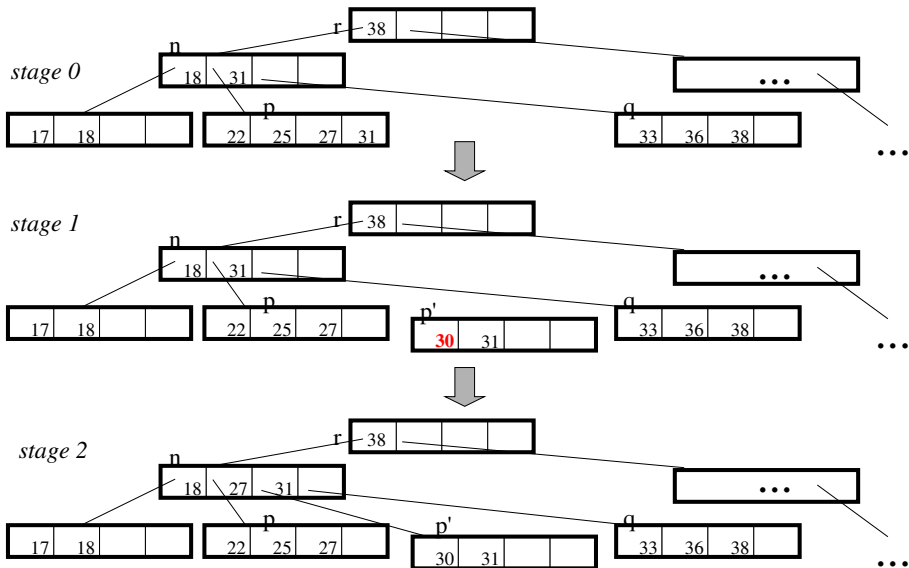
**Proof sketch:**

- $\text{search}(x)$  is in conflict with  $\text{insert}(y, \text{RID})$  or  $\text{delete}(y, \text{RID})$  only for  $x=y$ 
  - for successful search the conflict is detected by locks on  $x$
  - for unsuccessful search the conflict is detected by locks on largest key  $< x$
- $\text{range\_search}(\text{low}, \text{high})$  is in conflict with  $\text{insert}(y, \text{RID})$  or  $\text{delete}(y, \text{RID})$  if  $y$  falls into  $[\text{low}, \text{high}]$ 
  - this conflict is detected because  $\text{range\_search}$  incrementally acquires locks on all keys from  $\text{low}$  or the largest key  $< \text{low}$  up to and including the largest key  $\leq \text{high}$ , which must include the largest key  $< y$
- $\text{insert}(x, \text{RID})$  and  $\text{insert}(y, \text{RID})$  conflict only for  $x=y$  (and only for unique index)
- ...

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# Problem Scenario



**Problem:** *search(31) or insert(31) in between stage 1 and stage 2*



# Solution 1: Lock Coupling (“Crabbing”)

**Definition:** A tree node is **split-safe** if it has enough free space to accommodate at least one additional routing key and child pointer

## Protocol:

- Search operations need a read lock before accessing a node.  
Insert operations need a write lock before accessing a node.
- A lock can be granted only if there is no conflict and the requestor holds a lock (in the same mode) on the node's parent.
- Search operations can release a lock on a node once they have acquired a lock on a child of that node.
- Insert operations can release a lock on a node if
  - the node is split-safe and
  - they have acquired a lock on a child of that node

## Theorem 9.2:

Lock coupling for search and insert operations generates only OCSR schedules.

# Example: Lock Coupling

insert (30):

write lock r  
write lock n  
unlock r

write lock p  
allocate new page p'  
write lock p'  
split contents of p onto p and p'  
adjust contents of n  
release locks on n, p, p'

search (31):

read lock r  
request read lock on n

acquire read lock on n  
release lock on r  
read lock p'  
release lock on n  
return RID for key 31  
release lock on p'

# Lock Coupling with Range Searches, Next, and Delete Operations

- the initial *search (lowkey)* of a *range\_search (lowkey, highkey)* operation applies the locking rules for exact-key search operations
- a *next (currentkey, currentpage, highkey)* operation needs to acquire a read lock on *currentpage*, and it can acquire a lock on another leaf node only if it holds a lock on the preceding leaf.
  
- delete operations do *not* trigger node merging
- an empty node can be deallocated only when all transactions that were active at the time when the node became empty have terminated (“*drain technique*”)

# Correctness of Extended Lock Coupling

## Theorem 9.3:

Lock coupling with next operations generates only OCSR schedules.

## Theorem 9.4:

(Extended) Lock coupling at the page layer together with incremental key-range locking at the access layer ensure tree reducibility of all 2-level schedules.

## Proof sketch:

- By Theorems 9.1 and 9.3, schedules with search, insert, delete, and next operations are tree reducible.
- So the remaining problem scenario is of the form:  
... search<sub>i</sub> (lowkey) ... insert<sub>k</sub> (x, RID<sub>1</sub>) ... next<sub>i</sub> (currentkey<sub>1</sub>, ..., highkey) ...  
... insert<sub>i</sub> (y, RID<sub>2</sub>) ... next<sub>i</sub> (currentkey<sub>2</sub>, ..., highkey) ...  
with active transactions t<sub>i</sub>, t<sub>k</sub>, t<sub>i</sub>
- x cannot fall into [lowkey, currentkey<sub>1</sub>] and  
y cannot fall into [lowkey, currentkey<sub>2</sub>] because of previous-key lock conflicts
- So both insert<sub>k</sub> (x, ...) and insert<sub>i</sub> (y, ...) can be commuted to the left of t<sub>i</sub>

# Example: Extended Lock Coupling

range\_search (24, 35):

search (24)

read lock r, read lock n, unlock r

read lock p, unlock n

read lock key 22, unlock p

next (25, p, 35)

read lock p

read lock key 25, unlock p

next (27, p, 35)

request read lock on p

acquire lock on p

request read lock on key 27

acquire lock on key 27

read lock p', unlock p, unlock p'

next (30, p', 35)

read lock p', read lock key 30, unlock p'

...

insert (30):

write lock r, write lock n, unlock r

write lock p

write lock key 30, write lock key 27

release locks on p, p', n

commit transaction

## Solution 2: Link Technique

### Link protocol:

- Search operations need only lock the currently accessed node (no need for holding two page locks simultaneously)
- Upon “not found”, search and next operations proceed to the right sibling node until they have seen a larger key

## Solution 3: Giveup Technique

### Giveup protocol:

- All operations need only lock the currently accessed node (no need for holding two page locks simultaneously)
- Each node contains a “range field” for its subtree, maintained by splits on a per node basis
- Upon seeing a node with a range field that does not contain the search key, the operation “gives up” and is retried, starting again from the root

# Example: Link Technique

insert (30):

write lock r  
write lock n  
unlock r  
write lock p

allocate new page p'  
write lock p'  
split contents of p onto p and p'  
adjust contents of n  
release locks on n, p, p'

search (31):

read lock r  
release lock on r  
read lock n  
release lock on n

request read lock on p

acquire lock on p  
release lock on p  
read lock p'  
return RID for key 31  
release lock on p'

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# Further Optimizations

- Index traversal can use deadlock-free page latching rather than full-fledged locks
- Insert operations for the same key interval are commutative  
→ insert lock mode compatible with itself,  
but incompatible with read
- Insert operations merely need instant-duration lock on previous key
- Delete operations that leave a “ghost key” for deferred garbage collection need to lock only the deleted key
- Fewer locks (but possibly less concurrency)  
by locking (key, RID) pairs or only RIDs

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# Lessons Learned

- Index concurrency control is a perfect example for **layered schedules**
- At the **access layer**, a primitive form of predicate locking is used, namely, key-range locking, and optimized for incremental, low-overhead lock acquisition
- At the **page layer**, short-term locks or latches are used to isolate index operations, with protocols ranging from S2PL for subtransactions to lock coupling, link techniques, or give-up protocols
- Locking rules at the two levels are **integrated** with each other